

Planet Simulator

User's Guide

Version 16.0

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Chapter 1

Installation

The whole package containing the models "Planet Simulator" and "PUMA" along with "MoSt", the "Model Starter" comes in a single file, usually named "Most(n).tgz" with (n) specifying a version number. The following subsection gives an example, assuming version 16.

1.1 Quick Installation

```
tar -zxvf Most16.tgz
cd Most16
./configure.sh
./most.x
```
if your tar-command doesn't support the "-z" option (e.g. on Sun UNIX) type instead:

```
gunzip Most16.tgz
tar -xvf Most16.tar
cd Most16
./configure.sh
./most.x
```
If this sequence of commands produces error messages, consult the "FAQ" (Frequent Asked Questions) and README files in the Most16 directory. They are plain text files, that can be read with the command "more" or any text editor.

1.2 Most16 directory

```
home/Most16> ls -1G
```


-rw-r--r-- 1 1548 cc_check.c <- Used by configure.sh <- Delete run, bld and bin for PLASIM <- Delete run, bld and bin for PUMA \leftarrow Topography files $<-$ The configure script \leftarrow Currently unused -rw-r--r-- 1 234 f90check.f90 <- Used by configure.sh -rw-r--r-- 1 3033 FAQ <- Frequently Asked Questions \leftarrow Directory for images -rw-r--r-- 1 154 makecheck <- Used by configure.sh

The directory structure must not be changed, even empty directories must be kept as they are, the Most program relies on the existence of these directories!

For each model, currently "Planet Simulator" and "PUMA" exists a directory (plasim) and (puma) with following subdirectories:

```
Most16/plasim> ls -lg
```


After installation only "dat", "doc" and "src" contain files, all other directories are empty. Running "Most" to setup a model configuration and define an experiment uses the directories in the following manner:

1.3 Model build phase

Most writes an executable shell script to the "bld" directory and executes it directly hereafter. It copies all necessary source files from "src" to "bld" and modifies them according to the selected parameter configuration. Modification of source code is necessary for vertical and horizontal resolution change and for using more than 1 processor (parallel program execution). The original files in the "src" directory are not changed by Most. The program modules are then compiled and linked using the "make" command (in bld/most plasim build), also issued by Most. Most provides a makefile named make plasim for building the executable. For modules that exist in more than one version the selection of the module to use is done by environment variables that are set automatically by MoSt but may be changed manually by the user. Look into the make plasim for further information. The resolution and CPU parameters are coded into the filename of the executable, in order to have different names for different versions. E.g. the executable "most plasim t21 l10 p2.x" is an executable compiled for a horizontal resolution of T21, a vertical resolution of 10 levels and 2 CPU's. The executable is copied to the models "bin" directory after building. Each time Most is used to setup a new experiment it checks the "bin" directory for a matching executable. If it's there, it's used without rebuilding otherwise a new executable with the selected parameters is created. Rebuilding may be forced by using the cleanplasim command in the Most directory. The build directory is not cleared after usage. The user may want to modify the makefile or the build script for his own purposes and start the building directly by executing "most plasim build". For permanent user modifications the contents of the "bld" directories have to be copied elsewhere, because each usage of Most overwrites the contents of "bld".

1.4 Model run phase

After building the model with the selected configuration, Most writes or copies all necessary files to the model's "run" directory. These are the executable, initial and boundary data, namelist files containing the parameter and finally the run script itself. Depending on the exit from Most, either "Save & Exit" or "Run & Exit", the run script is started from Most and takes control of the model run. A checkmark on GUI invokes also the Graphical User Interface for user control and display of variables during the run. Again all contents of the "run" directory are subject of change for the user. But it would be wise to keep changed run setups in other, user created directories, because each usage of Most overwrites the contents of the run directory.

1.5 Running long simulations

For long simulations make a new directory on a filesystem, that has enough free disk space to store the results. You may use the "df" command to check filesystems.

Hint 1: Don't use your home directory if there are filequotas. Your run may crash due to file quota exceeded.

Hint 2: Use a local disk, not NFS mounted filesystems if possible. The model runs much faster writing output to local disks.

Example:

- cd Most16
- \bullet ./most.x
- Select model and resolution
- Switch GUI off
- Switch Output on
- Edit number of years to run
- Click on "Save & Exit"
- Make a directory, e.g. mkdir /data/longsim
- cp plasim/run/* /data/longsim
- cd /data/longsim
- edit most_plasim_run for experiment name
- edit namelist files if necessary
- start simulation with most plasim run $\&$

Chapter 2

Modules

In the following, the purposes of the individual modules is given and the general structure and possible input and output opportunities (namelist and files) are explained.

2.1 fluxmod.f90

General The module fluxmod.f90 contains subroutines to compute the different surface fluxes and to perform the vertical diffusion. The interface to the main PUMA module puma.f90 is given by the subroutines *fluxini*, *fluxstep* and *fluxstop* which are called in puma.f90 from the subroutines prolog, gridpointd and epilog, respectively.

Input/Output fluxmod.f90 does not use any extra input file or output file and is controlled by the namelist $fluxpar$ which is part of the namelist file puma_namelist:

Structure Internally, fluxmod.f90 uses the FORTRAN-90 module *fluxmod*, which uses the global common module *pumamod* from pumamod.f90. Subroutine *fluxini* reads the namelist and, if the parallel version is used, distributes the namelist parameters to the different processes. Subroutine *fluxstep* calls the subroutine *surflx* to compute the surface fluxes and calls the subroutine vdiff to do the vertical diffusion. Subroutine *fluxstop* is a dummy subroutine since there is nothing to do to finalize the computations in fluxmod.f90. The computation of the surface fluxes in \textit{surfx} is spitted into several parts. After initializing the stability dependent transfer coefficients, the subroutines *mkstress*, *mkshfl* and *mkevap* do the computations which are related to the surface wind stress, the surface sensible heat flux and the surface evaporation, respectively.

2.2 miscmod.f90

General The module miscmod.f90 contains miscellaneous subroutines which do not fit well to other modules. The interface to the main module plasim.f90 is given by the subroutines *miscini*, *miscstep* and *miscstop* which are called in puma.f90 from the subroutines prolog, gridpointd and epilog, respectively. A subroutine to eliminate spurious negative humidity and an optional subroutine to relax the upper level temperature towards a prescribed distribution is included in miscmod.f90.

Input/Output miscmod.f90 does not use any extra output file. If the relaxation is switched on, a climatological annual cycle of the prescribed upper level temperature distribution $[K]$ is read from the external file surface.txt. The file format is formatted SERVICE format with (8I10) for the headers and (8E12.6) for the temperature fields. To assign the field, the header needs to have the header information code 130, level 1 and a date identifier of the form *yymmdd* or mmdd where mm goes from 1 to 12 (January to December) or from 0 to 14 (including the December of the previous year and the January of the following year). Fields which are not needed will be skipped. The module is controlled by the namelist *miscpar* which is part of the namelist file puma_namelist:

Structure Internally, miscmod.f90 uses the FORTRAN-90 module *miscmod*, which uses the global common module *pumamod* from **pumamod.f90.** Subroutine *miscini* reads the namelist and, if the parallel version is used, distributes the namelist parameters to the different processes. If the relaxation is switched on, the climatological temperature is read from surface.txt and distributed to the processors. Subroutine miscstep calls the subroutine *fixer* to eliminate spurious negative humidity arising from the spectral method and, if the relaxation is switched on, calls the subroutine mknudge to do the temperature nudging. Subroutine miscstop is a dummy subroutine since there is nothing to do to finalize the computations in miscmod.f90.

2.3 surfmod.f90

General The module surfmod.f90 deals as an interface between the atmospheric part of the model and modules, or models, for the land and the oceans. The interface to the main PUMA module puma.f90 is given by the subroutines *surfini*, *surfstep* and *surfstop* which are called in puma.f90 from the subroutines prolog, gridpointd and *epilog*, respectively. Calls to subroutines named *landini*, *landstep* and *landstop* and seaini, seastep and seastop provide the interface to land and the ocean modules, respectively.

Input/Output surfmod.f90 reads the land-sea mask and the orography (surface geopotential) $\left[\text{m}^2/\text{s}^2\right]$ from file surface.txt. The file format is formatted SERVICE format with (8I10) for the headers and (8E12.6) for the fields. To assign the fields, the headers need to have the header information code 129 for the surface geopotential and 172 for the land-sea mask $(1.0 =$ land; $0.0 =$ sea). Fractional land-sea-masks containing other values than 1.0 and 0.0 will be converted with values > 0.5 set to 1.0 and all other to 0.0. surfmod.f90 is controlled by the namelist surfpar which is part of the namelist file puma namelist:

Structure Internally, surfmod.f90 uses the FORTRAN-90 module *surfmod*, which uses the global common module *pumamod* from **pumamod.f90.** Subroutine *surfini* reads the namelist and, if the parallel version is used, distributes the namelist parameters to the different processes. If the run is not started from a restart file, the land-sea-mask and the orography are read from file **surface.txt**. According to the namelist input, the orography is scaled by OROSCALE, transfered into spectral space and truncated to NOROMAX. Calls to subroutines *landini* and *seaini* are the interfaces to the respective initialization routines contained in the land and ocean modules. During the run, the interface to land and ocean is given by calls to the external subroutines *landstep* and *seastep*, which are called by *surfstep*. At the end of the integration, interface subroutines *landstop* and *seastop* are called by *surfstop*.

2.4 fftmod.f90 / fft991mod.f90

General The module fftmod.f90 contains all subroutines necessary to perform the fast fourier transformation and its inverse. The interface to the main module plasim.f90 is given by the subroutines $qp2fc$ and $fc2gp$ which are called in plasim.f90 from the subroutine gridpoint.

Input/Output fftmod.f90 does not use any extra input file or output file. No namelist input is required.

Structure Internally, fftmod.f90 uses the FORTRAN-90 module fftmod, which uses no other modules. Subroutine $qp2fc$ performs the transformation from grid point space into fourier space while the subroutine $fc2qp$ does the transformation from fourier space into grid point space. Both routines use several subroutines to do the direct or indirect transformation for different factors. When $qp2fc$ or $fc2gp$ is called for the first time, fftini is called to do the initialization of the FFT.

The alternate module fft991mod.f90 may be used instead of fftmod.f90. While fftmod.f90 runs faster fft991mod.f90 can be used for resolutions, that are not supported by fftmod.f90, e.g. T63 or T106. Edit the file $Most16/plasim/src/make-plasim$ for module selection. Use either

FFTMOD=fftmod

or

FFTMOD=fft991mod

2.5 landmod.f90

General The module landmod.f90 contains parameterizations for land surface and soil processes which include the simple biome model SIMBA and a model for the river runoff. The interface to the **Planet Simulator** is given via the module surfmod.f90 by the subroutines landini, landstep and landstop which are called in surfmod.f90 from the subroutines *surfini*, *surfstep* and *surfstop*, respectively.

Input/Output landmod.f90 reads several surface and soil parameters either from the initial file surface.txt or from the restart file plasim restart which is written at the end of an integration. surface.txt contains several surface fields which are needed for initialization. The file format is formatted SERVICE format with (8I10) for the header and (8E12.6) for the fields. The file may include the following fields: surface geopotential (orography) $\left[\text{m}^2/\text{s}^2\right]$, land-sea mask $\left[1.0,0.0\right]$, surface roughness [m], background albedo [frac.], glacier mask [frac.], bucket size [m], soil temperature [K], climatological annual cycle of the surface temperature [K], climatological annual cycle of the soil wetness [m]. To assign the fields, the headers need to have the header information code 129 for surface geopotential, code 172 for the land-sea mask $(1. = \text{land}; 0. = \text{sea})$, 173 for the surface roughness, 174 for the background albedo, 232 for the glacier mask $(1. = \text{glacier}; 0. = \text{no glacier})$, 229 for the bucket size, 209 for the soil temperature, 169 for the surface temperature and 140 for the soil wetness. for the climatological annual cycles of surface temperature and soil wetness, a date identifier of the form *yymmdd* or mmdd where mm goes from 1 to 12 (January to December) is required. Two additional months with mm=0 indicating the December of the preceding year an mm=13 for the January of the following year may be included for interpolation during transient simulations. If there are some fields not present in the **surface.txt** default values will be used which can be set in the namelist. The use of some fields depend on the setting of some namelist parameters. The restart file **plasim_restart** is an unformatted file which contains all variables needed to continue the run. landmod.f90 is controlled by the namelist *landpar* given in the namelist file **land_namelist**:

Structure Internally, landmod.f90 uses the FORTRAN-90 module *landmod*, which uses the global common module *pumamod* from **plasimmod.f90.** Subroutine *landini* reads the namelist and, if the parallel version is used, distributes the namelist parameters to the different processes. If the run is not started from a restart file, the initialization file **surface.txt** is being read. The soil and the river runoff are initialized via *soilini* and roffini and different variables are set according to the values given by the namelist or the surface.txt. Additionally, the climatological surface temperatures and soil wetnesses are updated from $\textbf{surface.txt}$ if NRESTART = 2. If NRESTART $= 3$ (special application) the bucket size, the roughness length and the albedo are set to the values given in the namelist. Subroutine landstep computes new surface and soil values via soilstep which calls tands and wandr for the heat and water budgets, respectively. If NLANDT and/or NLANDW are set to 0, climatological values are used for the surface temperature and the soil wetness. Via roffstep the river runoff is computed. Finally the biome model simbastep is called. The land model is finalized by *landstop* which writes the restart record to **plasim_restart**.

2.6 legmod.f90

General The module legmod.f90 contains all subroutines necessary to perform the Legendre transformation and its inverse. The interface to the main module plasim.f90 is given by the subroutines legini, inigau, $fc2sp$, $fc3sp$, and $sp2gp$ which are called in plasim.f90 from the subroutines *prolog* and *gridpoint*

Input/Output legmod.f90 does not use any extra input file or output file. No namelist input is required

The following subroutines are included in legmod.f90:

Subroutine Purpose

2.7 mpimod.f90 / mpimod stub.f90

General The module mpimod.f90 contains interface subroutines to the MPI (Message Passing Interface) needed for (massive) parallel computing. Several MPI routines are called from the module. The interface to other modules are given by numerous subroutines which names starts with mp. Subroutines from mpimod.f90 are called in sveral other modules. There are no direct calls to MPI other than in mpimod.f90. This encapsulation makes it possible to use mpimod stub.f90 for single CPU runs without changing any other part of the model code. The selection is done automatically by using MoSt or manually by editing "Most15/plasim/src/make plasim".

Input/Output mpimod.f90 and mpimod stub do not use any extra input file or output file. No namelist input is required

Structure Internally, mpimod.f90 uses the FORTRAN-90 module mpimod, which uses the global common module pumamod from plasimmod.f90 and the MPI module mpi. The following subroutines are included in mpimod.f90:

2.8 outmod.f90

General The module outmod.f90 controls the data output of the model. The interface to the main PUMA module puma.f90 is given by the subroutines *outini*, *outgp*, outsp, outreset and outaccu which are called in puma.f90 from the subroutines prolog and master.

Input/Output outmod.f90 writes the output data to the file puma_output which is an unformatted file. puma output is designed to be post processed by the program burn (see section [5\)](#page-44-0), which converts the model variables to useful output in user friendly format. There is no separate namelist for outmod.f90 but some parameter of namelist inp of plasim.f90 are used to control the format and the output interval.

Structure Internally, outmod.f90 uses the global common module *pumamod* from plasimmod.f90 in several subroutines. Subroutine outini does the initialization. Subroutines *outgp* and *outsp* write the grid point and the spectral fields to the output file **puma_output**. *outaccu* accumulates some output variables over the output interval. outreset resets the accumulated arrays to zero.

2.9 plasim.f90

General The module plasim.f90 is the main module of the model. It includes the main program *plasim* and controls the run. From **plasim.f90** the interface routines to the modules miscmod.f90, fluxmod.f90, radmod.f90, rainmod.f90, surfmod.f90 are called. The output is done by calling the interface routines to outmod.f90. In addition, the adiabatic tendencies and the horizontal diffusion are computed in plasim.f90. To do the necessary transformations, calls to the modules fftmod.f90 and legmod.f90 are used.

Input/Output plasim.f90 does not use any extra input file or output file. A diagnostic print out is written on standard output. plasim.f90 is controlled by the namelist inp which is part of the namelist file puma_namelist:

Structure Internally, plasim.f90 uses the FORTRAN-90 global common module pumamod from plasimmod.f90. After starting MPI, the main program plasim calls prolog for initializing the model. Then, master is called to do the time stepping. Finally, subroutine *epilog* finishes the run. In subroutine *prolog*, calls to different subroutines, which are part of plasim.f90 or are provided by other modules, initialize various parts of the model: *gauaw* and *inilat* build the grid, *readnl* reads the namelist and sets some parameter according to the namelist input, *initem* and *initsi* initialize some parameter for the physics and the semi implicit scheme, respectively. *outini* starts the output. If a file named **plasim_restart** exists all variables and arrays are read by restart, otherwise initfd sets the prognostic variables to their initial values. Calls to *miscini fluxini*, *radini*, *rainini* and *surfini* start the initialization of the respective external modules.i Finally, the global mean surface pressure is set according to PSURF (the observed value is 1011 hPa (Trenberth 1981) while 1013 is the ICAO standard) and the orography. Subroutine master controls the time stepping. First, if its not a restart, initial NKITS explicit forward timesteps are performed. The main loop is defined by calling *gridpointa* for the adiabatic tendencies, spectrala to add the adiabatic tendencies, gridpointd for the diabatic tendencies (which are computed by the external modules), spectrald to add the diabatic tendencies and the interface routines to the output module outmod.f90. The run is finalized by subroutine *epilog* which writes the restart records and calls the respective interface routines of the external modules.

2.10 plasimmod.f90

General The file plasimmod.f90 contains the module pumamod.f90 which declares all parameters and variables which may be used to share information between plasim.f90 and other modules. No subroutines or programs are included.

Input/Output pumamod.f90 does not use any extra input file or output file. No namelist input is required

Structure Internally, plasimmod.f90 is a FORTRAN-90 module named pumamod. Names for global parameters, scalars and arrays are declared and, if possible, values are preset.

2.11 radmod.f90

General The module radmod.f90 contains subroutines to compute radiative energy fluxes and the temperature tendencies due to long wave and short wave radiation. The interface to the main PLASIM module plasim.f90 is given by the subroutines radini, radstep and radstop which are called in **plasim.f90** from the subroutines prolog, gridpointd and epilog, respectively.

Input/Output radmod.f90 does not use an extra output file. If the Switch for ozone (NO3, see namelist) is set to 2 (externally prescribed), the climatological cycle of the ozone distribution is read from the external file **surface**.txt which name is given in the namelist. The file format is formatted SERVICE format with (8I10) for the header and $(8E12.6)$ for the fields. To assign the fields, the headers need to have the header information code 200, level going from 1 to NLEV and a date identifier of the form yymmdd or mmdd where mm goes from 01 to 12 (January to December). radmod.f90 is controlled by the namelist *radpar* which is part of the namelist file puma namelist:

Structure Internally, radmod.f90 uses the FORTRAN-90 module *radmod*, which uses the global common module *pumamod* from **plasimmod.f90**. Additionally, the FORTRAN-90 module orbparam is used. Subroutine radini reads the namelist and, if the parallel version is used, distributes the namelist parameters to the different processes. Orbital parameters are computed by calling orb params. If NO3 is set to 2, the ozone distribution is read from surface.txt. Subroutine radstep calls the subroutines *solang* and $mko3$ to compute the cosine of the solar angle and the ozone distribution, respectively. The short wave radiative fluxes are calculate in swr while the long wave radiative fluxes are computed in lwr. Subroutine radstop is a dummy subroutine since there is nothing to do to finalize the computations in radmod.f90.

2.12 rainmod.f90

General The module rainmod.f90 contains subroutines to compute large scale and convective precipitation and the related temperature tendencies. In addition, a parameterization of dry convective mixing of temperature and moisture is included and cloud cover is diagnosed. The interface to the main PLASIM module plasim.f90 is given by the subroutines *rainini*, *rainstep* and *rainstop* which are called in puma.f90 from the subroutines prolog, gridpointd and epilog, respectively.

Input/Output rainmod.f90 does not use any extra input or output file and is controlled by the namelist *rainpar* which is part of the namelist file **puma_namelist**:

Structure Internally, rainmod.f90 uses the FORTRAN-90 module rainmod, which uses the global common module *pumamod* from plasimmod.f90. Subroutine *rainini* reads the namelist and, if the parallel version is used, distributes the namelist parameters to the different processes. Subroutine rainstep calls the subroutine mkdqdtgp to obtain the adiabatic moisture tendencies in grid point space, which are needed for the Kuo parameterization. kuo is called to compute the convective precipitation and the respective tendencies. Dry convective adjustment is performed in *mkdca*. Large scale precipitation is computed in mklsp. Finally, diagnostic clouds are calculated in mkclouds. Subroutine radstop is a dummy subroutine since there is nothing to do to finalize the computations in radmod.f90.

2.13 seamod.f90

General The module seamod.f90 is the interface from the atmosphere to the ocean and the sea ice. The interface to the main PLASIM module puma.f90 is given by the subroutines *seaini*, *seastep* and *seastop* which are called in puma.f90 from the subroutines *prolog, gridpointd* and *epilog* respectively.

Input/Output seamod.f90 reads different surface parameters either from the file surface.txt (see namelist) and the file ocean parameter or from the restart file sea_restart which is written at the end of an integration.. The files formats are unformatted for the restart file, formatted SERVICE format with (8I10) for the header and $(8E12.6)$ for the fields for **surface.txt** and formatted EXTRA format with $(4I10)$ for the header and $(6(1X, E12.6))$ for the fields for **ocean parameter**. The file surface.txt may include the following fields: The climatological annual cycle of the surface temperature $[K]$ and the climatological annual cycle of the sea ice compactness [frac.]. To assign the fields, the headers need to have the header information code 169 for surface temperature and code 210 for the compactness $(1 = ice; 0. = open water)$. a date identifier of the form *yymmdd* or mmdd where mm goes from 1 to 12 (January to December) is required. Fields which are not needed will be skipped. The file **ocean parameter** includes the following fields: The climatological annual cycle of the sea surface temperature [K], the climatological annual cycle of the mixed layer depth [m] and the climatological average of the deep ocean temperature [m]. To assign the fields, the order must be as described above (no header information is used). The restart file sea_restart contains all variables needed to continue the run. seamod.f90 is controlled by the namelist *seapar* given in the namelist file sea namelist:

Structure Internally, seamod.f90 uses the FORTRAN-90 module seamod, which uses the global common module *pumamod* from plasimmod.f90. Subroutine *seaini* reads the namelist and, if the parallel version is used, distributes the namelist parameters to the different processes. If it is not a restart (i.e. if NRESTART from inp of plasimmod.f90 is (0) , the files surface.txt and ocean parameter are being read. The climatological sea ice compactness is converted to a sea ice thickness as initial condition and additional surface parameters are set. If it is a restart, the restart file sea restart is read. Subroutine *seastep* accumulates the variables used for the coupling between the atmosphere and the ocean. The coupling is done via the sea ice model. There is no direct connection between atmosphere and ocean model. If there is no sea ice, the coupling quantities are passed through the ice model without changes. Subroutine seastop finalizes the run and writes the restart records.

2.14 Sea ice and ocean modules

This section describes the modules that represent sea ice and ocean and the necessary interfaces between these modules and the atmospheric modules. Conceptually, the sea ice model lies inbetween the atmosphere model and the ocean model. Thus, the PUMA main part and the ocean model are both coupled to the sea ice model, but not directly to each other. The sea ice model decides whether a given gridpoint is covered with ice or not, in the latter case, it merely functions as passing the ocean fluxes to the atmosphere and vice versa. The parameters that are exchanged are listed in Table [2.1.](#page-29-1) The sea ice and ocean model use a time step of one day. Thus, atmospheric coupling to the sea ice model is performed every 32 time steps, while the sea ice and ocean model are coupled every time step. The coupling scheme is shown in Fig. [2.1.](#page-30-0) Fig. [2.2](#page-31-0) shows how the subroutines are placed when no external coupler is used.

Table 2.1: Parameters to be exchanged between models. Arrows denote the direction in which the parameter is passed, e.g. the atmosphere receives ice cover information from the ice model.

Figure 2.1: Schematic illustration of the model coupling.

Figure 2.2: Subroutine flow when no external coupler is used.

2.15 icemod.f90

General The module icemod.f90 contains subroutines to compute sea ice cover and thickness. The interface to the main PLASIM module is given by the subroutine icestep, which is called by cplexchange_ice (defined in intermod_atm.f90), which is called by *seastep* (defined in seamod.f90).

Input/Output icemod.f90 requires the file ice_flxcor if NFLXCORR is set to a negative value. If NOUTPUT is set to 1, the output files fort.75 containing global fields of ice model data and the file fort.76 containing diagnostic ice data are produced (for details, see the reference manual). Both output files are in service format. The module is controlled by the namelist icepar in the file ice_namelist.

Structure icemod.f90 uses the module icemod which is not dependent on the module *pumamod*. Subroutine *iceini* reads the namelist and, when required, the flux correction from the file ice_flxcor. Subroutine *icestep* calls cplexchange_atmos (defined in intermod_ice) to get the atmospheric forcing fields. If the sea_namelist parameter NICE is set to 1, the subroutine subice is called, which calculates ice cover and thickness. Otherwise, climatological data, interpolated to the current time step by iceget are used. If an ice cover is present, the surface temperature is calculated in skintemp. Otherwise, the surface temperature is set to the sea surface temperature calculated by the ocean model. Every NCPL_ICE_OCEAN (defined in sea_namelist) time steps, the external subroutine cplexchange_ocean (defined in intermod_ice) is called to pass the atmospheric forcing to and retrieve oceanic data from the ocean module oceanmod.f90. The oceanic data is used for ice calculations in the next time step.

2.16 oceanmod.f90

General The module oceanmod.f90 contains a mixed layer ocean model, i.e. subroutines to compute sea surface temperature and mixed layer depth. The interface to the main PLASIM module is via the module icemod.f90 given by the subroutine oceanstep, which is called by cplexchange_ocean (defined in intermod_ice).

Input/Output oceanmod.f90 requires the file ocean_flxcor if NFLX-CORRSST or NFLXCORRMLD is set to a negative value. If NOUTPUT is set to 1, the output file fort.31 containing global fields of ocean model data in service format is produced (for details, see the ice modul section of the reference guide). The module is controlled by the namelist oceanpar in the file ocean_namelist.

Structure oceanmod.f90 uses the module *oceanmod* which is not dependent on the module pumamod. Subroutine oceanini reads the namelist and, when required, the flux corrections from the file **ocean_flxcor**. Subroutine *oceanstep* calls mixocean, which calculates mixed layer depth and temperature. If an ice cover is present, mixed layer depth is set to the climatological value and the sea surface temperature is set to the freezing temperature. For details of the mixed layer model, see the Planet Simulator Reference Manual.

Chapter 3

Parallel Program Execution

3.1 Concept

The Planet Simulator is coded for parallel execution on computers with multiple CPU's or networked machines. The implementation uses MPI (Message Passage Interface), that is available for nearly every operating system <http://www.mcs.anl.gov/mpi>.

In order to avoid maintaining two sets of source code for the parallel and the single CPU version, all calls to the MPI routines are encapsulated into a module. Users, that want to compile and execute the parallel version use the module mpimod.f90 and the commands mpif90 for compiling and mpirun for running.

If MPI is not implemented or the single CPU version is sufficient, **mpimod_stub.f90** is used instead of mpimod.f90. Also remove or comment the line:

! use mpi

and set the number of processors to 1:

parameter(NPRO = 1)

3.2 Parallelization in Gridpoint Domain

The data arrays in gridpoint domain are either three-dimensional e.g. gt(NLON, NLAT, NLEV) referring to an array organized after longitudes, latitudes and levels, or two-dimensional, e.g. gp(NLON, NLAT). The code is organized such, that there are no dependencies in latitudinal direction, while in gridpoint domain. Such dependencies are resolved during the Legendre-Transformations. So the the partitioning of the data is done in latitudes. The program can use as many CPU's as latitudes with the extreme of every CPU doing the computations for a single latitude. There is the restriction however, that the number of latitudes (NLAT) divided by the number of processors (NPRO), giving the number of latitudes per process (NLPP) must have zero remainder. E.g. A T31 resolution uses $NLAT = 48$. Possible values for NPRO are then 1, 2, 3, 4, 6, 8, 12, 16, 24, and 48.

All loops dealing with a latitudinal index look like:

do jlat = 1 , NLPP enddo

There are, however, many subroutines, with the most prominent called calcgp, that can fuse latitudinal and longitudinal indices. In all these cases the dimension NHOR is used. NHOR is defined as: $NHOR = NLON * NLPP$ in the pumamod - module. The typical gridpoint loop that looks like:

```
do jlat = 1, NLPP
  do jlon = 1, NLON
      gp(jlon,jlat) = ...enddo
enddo
```
is then replaced by the faster executing loop:

```
do jhor = 1, NHOR
  gp(jhor) = ...enddo
```
3.3 Parallelization in Spectral Domain

The number of coefficients in spectral domain (NRSP) is divided by the number of processes (NPRO) giving the number of coefficients per process (NSPP). The number is rounded up to the next integer and the last process may get some additional dummy elements, if there is a remainder in the division operation.

All loops in spectral domain are organized like:

```
do jsp = 1, NSPP
   sp(jsp) = ...enddo
```
3.4 Synchronization points

All processes must communicate and have therefore to be synchronized at following events:

- Legendre-Transformation: This involves changing from latitudinal partitioning to spectral partitioning and such some gather and scatter operations.
- Inverse Legendre-Transformation: The partitioning changes from spectral to latitudinal by using gather, broadcast, and scatter operations.
- Input-Output: All read and write operations must be done only by the root process, who gathers and broadcasts or scatters the information as desired. Code that is to be executed by the root process exclusively is written like:

```
if (mypid == NROOT) then
   ...
endif
```
NROOT is typically 0 in MPI implementations, mypid (My process identification) is assigned by MPI.

3.5 Source code

It needs some discipline in order to maintain parallel code. Here are the most important rules for changing or adding code to the Planet Simulator:

- Adding namelist parameters: All namelist parameters must be broadcasted after reading the namelist. (Subroutines mpbci, mpbcr, mpbcin, mpbcrn)
- Adding scalar variables and arrays: Global variables must be defined in a module header and initialized.
- Initialization code: Initialization code, that contains dependencies on latitude or spectral modes must be done by the root process only and then scattered from there to all child processes.
- Array dimensions and loop limits: Always use parameter constants (NHOR, NLAT, NLEV, etc.) as defined in pumamod.f90 for array dimensions and loop limits.
- Testing: After significant code changes the program should be tested in single and in multi-CPU configuration. The results of a single CPU run is usually not exactly the same as the result of a multi-CPU run due to effects in rounding. But the results should show only small differences during the first timesteps.
- Synchronization points: The code is optimzed for parallel execution and minimizes therefore communication overhead. The necessary communication code is grouped around the Legendre-transformations. If more scatter/gather operations or other communication routines are to be added, they should be placed just before or after the execution of the calls to the Legendre-Transformation. Any other place would degrade the overall performance in introducing additional process synchronization.

Chapter 4

Graphical User Interface

4.1 Graphical user interface (GUI)

The Planet Simulator may be used in the traditional fashion, with shell scripts, batch jobs, and network queuing systems. This is acceptable for long running simulations on complex machines and number-crunchers, like vector- computers, massive-parallel-computers and workstation clusters. There is now, however, a much more convenient method by using a graphical user interface (GUI) for model setup with parameter configurations and for interaction between user and model.

The Planet Simulator is configured and setup by the first GUI module named MoSt (Model Starter, screenshot in [4.1\)](#page-39-0). MoSt is the fastest way to get the model running. It gives access to the most important parameters of the model preset to the most frequently used values. The model can be started with a mouse click on the button labelled "Save & Run" either with the standard paramater setting or after editing some of the parameters in the MoSt window. Some parameters, like horizontal and vertical resolution, or the number of processors, require the building (compile, link and load) of new executables. MoSt achieves this by generating and executing build scripts, that perform the necessary code changes and create the required executable. Other parameters define startup- and boundary conditions or settings for parameterisations. They can be edited in MoSt and, after a check for correct range and consistency with other parameters, are written to the model's namelist file.

Depending on all settings MoSt generates a runscript for the simulation. The user has the choice of leaving MoSt and continue with the simulation under control of a GUI right away, or to exit MoSt with the scripts prepared to run. The second alternative is useful for users, who want to modify the setup beyond the scope of MoSt or want to run the Planet Simulator without GUI.

There's also a simple graphical editor for topograpy. Check the box Orography and then use the mouse to mark rectangular areas in the topography display. Enter a value for rising (positive) or lowering the area and press the button labelled Preprocess. The preprocessor will be built and executed, a new topography will be computed and written to a start file.

Another editor is the mode editor for spherical harmonics. Green modes are enabled, red modes are disabled. This feature can be used to make runs with only certain modes of spherical harmonics being active. MB1, MB2, MB3 refer to the left, middle, and right mouse button. You may toggle individual modes or whole lines and columns. Currently this mode editor can only be used for Planet Simulator in the T21 resolution.

The GUI for running the Planet Simulator (screenshot in [4.2\)](#page-39-1) has two main purposes. The first one is to display model arrays in suitable representations. Current implementations are:

• Zonal mean cross sections

Figure 4.1: Screenshot of Model Starter (MoSt)

Figure 4.2: Screenshot of Graphical User Interface (GUI)

- Horizontal global fields in cylinder projection
- Horizontal global fields in polar projection
- Time-longitude (Hovmoeller) diagrams
- Amplitudes of coefficients of spherical harmonics
- Time series
- Numerical values

In case of horizontal global grids pressing the MMB (Middle Mouse Button) toggles between cylinder and polar projection. If the grid is just one level from many of a three dimensional field like u or v, the level shown can be decreased by the LMB or increased by the RMB. For Hovmoeller and longitude height sections the LMB and RMB can be used to select the latitude.

The second purpose is the interaction part of the GUI, which allows the user to change selected model variables during the model run. It is not necessary, though possible, to pause the model while changing variables. Changes to model variables are, of course, monitored in the outputfile and checked by GUI for the appropriate range of values and maximum possible change per timestep because, otherwise, a rapid parameter change or a choice of values beyond the normal range may blow up the model.

All model variables, which are candidates for the display or interactive changes, have a special code to communicate with the Planet Simulator. The experienced modeller can add new code for more variables using the existing communication code as template. Thus all model fields or even fields received via coupling with other models can be put on the GUI display.

Both, MoSt and GUI are implemented using the Xlib (X11R5), which is a library of routines for graphics and event communication. As this library is part of every UNIX/Linux operating system and base of all desktop environments, there is no need to install additional software for running MoSt and GUI. Another important property of Xlib is the full network transparency. The display of MoSt and GUI is not locked to the machine running the programs or the model. In fact, the best performance is obtained in running the Planet Simulator on two or four CPUs of a remote server while displaying the GUI on the user's workstation. In summarizing, the MoSt and GUI programs automate many tedious tasks, minimize the time to become familiar with the Planet Simulator, and make debugging and parameter tuning much easier. More kinds of presentations, coordinate projections and interactivity are being developed. A graphical preprocessor with editor for boundary conditions and a graphical postprocessor are future expansions to build an almost complete environment for modellers.

4.2 GUI configuration

On initialization the GUI reads its configuration from a file GUI.cfg which must be present in the current directory. MoSt copies the file $\bf GUI.cfg$ from the $./\rm dat/$ directory to the run directory while building the **Planet Simulator**. After reading **GUI.cfg** an attempt is made to read the file **GUI** last used.cfg. This file is always written at the end of a GUI controlled simulation. So one may rearrange and position GUI windows during a run and the new layout will be saved to the file GUI last used.cfg. In order to make this user layout default for following runs, just copy this file like:

Most15/plasim/run\$ cp ../dat/GUI.cfg ../dat/GUI.cfg.old Most15/plasim/run\$ cp GUI_last_used.cfg ../dat/GUI.cfg

MoSt will then copy your new layout to the run directory at the next invocation.

The **GUI.cfg** is a text file that may be also edited manually. There is a section for each window (counting from 0 to 8) which looks like:

```
[Window 00] <- window number (0..8)
Array: CSU <- array name
Plot:ISOCS <- picture type
Palette:U <br>
Title:Zonal Wind [m/s] <br>
Title:Zonal Wind [m/s] <br>
<- window title
Title: Zonal Wind [m/s]Geometry: 529 299 2 3 <- width height left top
[Window 01]
Array:SPAN
Plot:ISOSH
Palette:AMPLI
Title:Spherical Harmonics Ps
Geometry: 529 299 535 3
...
```
Possible values for these items are:

4.2.1 Array

4.2.2 Plot

4.2.3 Palette

4.2.4 Title

The title item may contain any text, but keep it short, the length of the window's title bar is limited. The words *Latitude* and *Level* have special features in conjunction with threedimensional arrays, where the user may scroll the level or latitude. The GUI will insert the level number after the world Level or the latitude after the word Latitude.

4.2.5 Geometry

The four integers following the geometry item describe the size and screen position of the window. The first two parameters refer to width and height in screen pixel. These are the sizes of the inner window, title bar, border and other decorations are not counted. The third and fourth parameter set the coordinates of the upper left corner of the window x and y, again without borders. If the geometry item is not defined, the GUI will initialize the window's geometry depending on the screen size.

Chapter 5

Postprocessor Pumaburner

5.1 Introduction

The Pumaburner is a postprocessor for the Planet Simulator and the PUMA model family. It's the only interface between raw model data output and diagnostics, graphics, and user software.

The output data of the **Planet Simulator** are stored as packed binary (16 bit) values using the model representation. Prognostic variables like temperature, divergence, vorticity, pressure, and humidity are stored as coefficients of spherical harmonics on σ levels. Variables like radiation, precipitation, evaporation, clouds, and other fields of the parameterization package are stored on Gaussian grids.

The tasks of the Pumaburner are:

- Unpack the *raw* data to full real representation.
- Transform variables from the model's representation to a user selectable format, e.g. grids, zonal mean cross sections, fourier coefficients.
- Calculate diagnostic variables, like vertical velocity, geopotential height, wind components, etc.
- Transfrom variables from σ levels to user selectable pressure levels.
- Compute monthly means and standard deviations.
- Write selected data either in SERVICE, GRIB, or NetCDF format for further processing.

5.2 Usage

```
pumaburn4 [options] InputFile OutputFile <namelist >printout
     option -h : help (this output)
     option -c : print available codes and names
     option -d : debug mode (verbose output)
     option -g : Grib output (override namelist option)
     option -n : NetCDF output (override namelist option)
     option -m : Mean=1 output (override namelist option)
     InputFile : Planet Simulator or PUMA data file
    OutputFile : GRIB, SERVICE, or NetCDF format file
      namelist : redirected <stdin>
      printout : redirected <stdout>
```
5.3 Namelist

The namelist values control the selection, coordinate system and output format of the postprocessed variables. Names and values are not case sensitive. You can assign values to the following names:

5.4 HTYPE

HTYPE accepts the first character of the following string. Following settings are equivalent: $HType = S$, $HType = Spherical Harmonics HType = Something$. Blanks and the equal-sign are optional.

Possible Values are:

5.5 VTYPE

VTYPE accepts the first character of the following string. Following settings are equivalent: $VTYPE = S$, $VTYPE = Sigma VTYPE = Super$. Blanks and the equal-sign are optional. Possible Values are:

տուտը ւտաշ այ,				
Setting	Description	Remark		
		$VTYPE = S$ Sigma (model) levels Some derived variables are not available		
	$VTYPE = P $ Pressure levels	Interpolation to pressure levels		

5.6 MODLEV

MODLEV is used in combination with $VTYPE = S$. If VTYPE is not set to Sigma, the contents of MODLEV are ignored. MODLEV is an integer array that can get as many values as there are levels in the model output. The levels are numbered from top of the atmosphere to the bottom. The number of levels and the corresponding sigma values are listed in the pumaburner printout. The outputfile orders the level according to the MODLEV values. MODLEV $=1,2,3,4,5$ produces an output file of five model levels sorted from top to bottom, while MODLEV= $5,4,3,2,1$ sorts them from bottom to top.

5.7 hPa

hPa is used in combination with $VTYPE = P$. If VTYPE is not set to Pressure, the contents of hPa are ignored. hPa is a real array that accepts pressure values with the units hectoPascal or millibar. All output variables will be interpolated to the selected pressure levels. There is no extrapolation on the top of the atmosphere. For pressure values, that are lower than that of the model's top level, the top level value of the variable is taken. The variables temperature and geopotential height are extrapolated if the selected pressure is higher than the surface pressure. All other variables are set to the value of the lowest mode level for this case. The outputfile contains the levels in the same order as set in hPa . Example: $hpa =$ 100,300,500,700,850,900,1000.

5.8 MEAN

MEAN can be used to compute montly means and/or deviations. The Pumaburner reads date and time information from the model file and handles different lengths of months and output intervals correctly.

5.9 Format of output data

The pumaburner supports three different output formats:

- GRIB (GRIdded Binary) WMO standard for gridded data.
- NetCDF (Network Common Data Format)
- **Service** Format for user readable data (see below).

IIUUD://WWW.IIWS.IIOdd.gov/Oll/OIQ/IOD/NUAAPURI/IeSOUICeS/			
Description			
	$GRIB = 1$ NetCDF = 0 The output file is written GRIB format. This option		
	can be used only for HTYPE=Spherical Harmonics or		
	HTYPE=Gauss Grid.		
	$GRIB = 0$ NetCDF = 1 The output file is written in NetCDF format. This op-		
	tion can be used for HTYPE=Gauss Grid only.		
$GRIB = 0$	\vert NetCDF = 0 \vert The output file is written in Service format. This is		
	the preferred format for user programs. For a detailed		
	description see the following section.		
	$GRIB = 1$ NetCDF = 1 Illegal combination.		

For more detailed descriptions see for example: h_{max}/m / h_{max}/m / h_{max}/N

5.10 SERVICE format

The SERVICE format uses the following structure: The whole file consists of pairs of header records and data records. The header record is an integer array of 8 elements.

```
head(1) = ECMWF field code
   head(2) = modellevel or pressure in [Pa]head(3) = date [yymmdd] (yymm00 for monthly means)
   head(4) = time [hhmm] or [hh] for HHMM=0
   head(5) = 1. dimension of data array
   head(6) = 2. dimension of data array
   head(7) = may be set with the parameter HEAD7head(8) = experiment number (extracted from filename)
    Example for reading the SERVICE format (GRIB=0 , NETCDF=0)
    INTEGER HEAD(8)
   REAL FIELD(64,32) ! dimensions for T21 grids
   READ (10,ERR=888,END=999) HEAD
   READ (10,ERR=888,END=999) FIELD
    ....
888 STOP 'I/O ERR'
999 STOP 'EOF'
    ....
```
5.11 HHMM

5.12 HEAD7

The 7th. element of the header is reserved for the user. It may be used for experiment numbers, flags or anything else. Setting HEAD7 to a number exports this number to every header record in the output file (SERVICE format only).

5.13 MARS

This parameter is used for processing simulations of the Mars atmosphere. Setting MARS=1 switches gravity, gas constant and planet radius to the correct values for the planet Mars.

5.14 MULTI

The parameter MULTI can bes used to process a series of input data within one run of the pumaburner. Setting MULTI to a number (n) tells the pumaburner to procees (n) input files. The input files must follow one of the following two rules:

• YYMM rule: The last four characters of the filename contain the data in the form YYMM.

• .NNN rule: The last four characters of the filename consist of a dot followed ny a 3-digit sequence number.

Examples:

```
Namelist contains MULTI=3
Command: pumaburn <namelist >printout run.005 out
pumaburn processes the files <run.005> <run.006> <run.007>
Namelist contains MULTI=4
Command: pumaburn <namelist >printout exp0211 out
pumaburn processes the files <exp0211> <exp0212> <exp0301> <exp0302>
```
5.15 Namelist example

```
VTYPE = Pressure
HTYPE = GridCODE = 130, 131, 132hPa = 200,500,700,850,1000MFAN = 0GRIB = 0NETCDF = 0
```
This namelist will write Temperature(130), $u(130)$ and $v(131)$ on pressure levels 200hPa, 500hPa, 700hPa, 850hPa and 1000hPa. The output interval is the same as found on the model data, e.g. every 12 or every 6 hours (MEAN=0). The output format is SERVICE format.

5.16 Troubleshooting

If the pumaburner reports an error or doesn't produce the expected results, try the following:

- Check your namelist, especially for invalid codes, types and levels.
- Run the pumaburner in debug-mode by using the option -d. Example:

```
pumaburn <namelist >printout -d data.in data.out
```
This will print out some details like parameters and memory allocation during the run. The additional information may help to detect the problem.

• Not all combinations of HTYPE, VTYPE, and CODE are valid. Try to use HTYPE=Grid and VTYPE=Pressure before switching to exotic parameter combinations.

Chapter 6

Graphics

6.1 Grads

In this section, visualisation using the graphics package GrADS is described. A useful Internet site for reference and installation instructions is

<http://grads.iges.org/grads/grads.html>.

Latest versions of GrADS can handle data in NETCDF format (via the command sdfopen), GRIB, HDF-SDS, and in its native binary format. The native format can conveniently be derived from SERVICE format. In the following it is assumed that the PUMA output has been converted to SERVICE format with the pumaburner and the resulting file is called puma.srv. Monthly mean data is either obtained directly from the pumaburner (namelist parameter MEAN=1, see section [5\)](#page-44-0) or via a PINGO command:

srv monmeans puma.srv puma_m.srv

Information on the PINGO package can be found in DKRZ report 11 at

<http://www.mad.zmaw.de/Pingo/repdl.html>.

The SERVICE file has to be converted to GrADS's native format by the command:

srv2gra puma_m.srv

which results in the files puma_m.gra and puma_m.ctl. The first file contains the data, the latter one information on the grid, time steps, and variable names. The program srv2gra is one of the postprocessing tools available at

<http://puma.dkrz.de/puma/download/map/>.

If you chose to compile it yourself, please read the comments in the first few lines of the program text. Sometimes the srv2gra tool has difficulties to calculate an appropriate time increment from the date headers of the data records, so you should check this. In this example the file puma_m.ctl should look like this:

```
DSET ^puma_m.gra
UNDEF 9e+09
XDEF 64 LINEAR 0.0000 5.6250
OPTIONS YREV
YDEF 32 LEVELS
 -85.7606 -80.2688 -74.7445 -69.2130 -63.6786 -58.1430 -52.6065 -47.0696
```


Here, the line starting with TDEF ends with 1mo, since we are handling monthly mean data. When the PUMA output is used without averaging, this should correspond to the output interval given by the nafter variable used in the namelist of your PUMA run (see section [C\)](#page-64-0). The number of variables depends on how the pumaburner was called. In this example, only 3 variables were processed, i.e. the surface temperature (c139), the sea level pressure (c151) and the albedo (c175; refer to appendix [B](#page-62-0) for a list of codes).

The GrADS program is started by typing grads in a terminal window. Then, data is visualised either by typing commands line-by-line, or, preferably, by using scripts. The following script, called tglob.gs, displays the monthly mean surface temperature:

```
# tglob.gs
function pass(m)
'reinit'
'open puma_m'
'enable print print.mf'
'set t 'm
\mathfrak{c}'set gxout shaded'
'd (c139-273.16)'
'cbar.gs'
'set gxout contour'
'd (c139-273.16)'
'draw title Surface Temperature (deg C) month 'm
'print'
'disable print'
'!gxps -i print.mf -o tglob'm'.ps'
```
The variable m at the beginning of the script defines the month which should be displayed. It is passed from the terminal with the script call. Note that in this line, no quotation marks are present, since only GrADS specific commands are framed by quotation marks. Script commands, like variable definitions, if-clauses etc. are used without quotation marks. The script is executed by typing its name without the ending and the number of the month to be shown. For example, tglob 7 displays the monthly mean surface temperature in July. The resulting output file is called tglob7.ps.

The following script thh displays the time dependent surface temperature of Hamburg. Here, two variables are passed to GrADS, the first and last day to plot (note that here, the file puma.gra is opened, which contains data on a daily basis). The call thh 91 180 displays the surface temperature of Hamburg for the spring season from April 1st to June 30th.

thh.gs

```
function pass(d1 d2)
'reinit'
'open puma'
'enable print print.mf'
'set lat 53'
'set lon 10'
'set t 'd1' 'd2
\cdot c''d (c139-273.16)'
'draw title Surface Temperature (deg C) in Hamburg'
'print'
'disable print'
'!gxps -i print.mf -o thh.ps'
```
It is possible to have more than one figure in a plot, which is illustrated in the following script. It plots seasonal means of the sea level pressure. The data file is prepared like this:

```
srv selcode,151 puma.srv slp.srv
srv seasmean slp.srv slp_sm.srv
srv2gra slp_sm.srv
```
The commands set vpage sets virtual pages inside the graphic window. The full window is 11 inch wide and 8.5 inch high, so set vpage 0 5.5 4.25 8.5 defines the upper left corner. If setlevs=1 is specified, the pressure levels as given are used. Otherwise, GrADS defines contour levels depending on the data set.

```
# slp_sm.gs
setlevs=1
'reinit'
'open slp_sm'
'enable print print.mf'
\overline{C}'set vpage 0 5.5 4.25 8.5'
'set gxout contour'
if (setlevs=1)
'set clevs 990 995 1000 1005 1010 1015 1020'
endif
'set ccols 1'
'set grads off'
'set t 1'
'd c151/100'
'draw title SLP [hPa] yr 'ny' DJF'
'set vpage 5.5 11 4.25 8.5'
'set gxout contour'
if (setlevs=1)
'set clevs 990 995 1000 1005 1010 1015 1020'
endif
'set ccols 1'
'set grads off'
'set t 2'
```

```
'd c151/100'
'draw title yr 'ny' MAM'
'set vpage 0 5.5 0 4.25'
'set gxout contour'
if (setlevs=1)
'set clevs 990 995 1000 1005 1010 1015 1020'
endif
'set ccols 1'
'set grads off'
'set t 3'
'd c151/100'
'draw title yr 'ny' JJA'
'set vpage 5.5 11 0 4.25'
'set gxout contour'
if (setlevs=1)
'set clevs 990 995 1000 1005 1010 1015 1020'
endif
'set ccols 1'
'set grads off'
'set t 4'
'd c151/100'
'draw title yr 'ny' SON'
'print'
'disable print'
'!gxps -c -i print.mf -o slp_sm.ps'
```
6.2 Vis5D

"Vis5D is a system for interactive visualization of large 5-D gridded data sets such as those produced by numerical weather models. One can make isosurfaces, contour line slices, colored slices, volume renderings, etc of data in a 3-D grid, then rotate and animate the images in real time. There's also a feature for wind trajectory tracing, a way to make text annotations for publications, support for interactive data analysis, etc."

> from the Vis5D home page, <http://www.ssec.wisc.edu/~billh/vis5d.html>

This powerful visualisation tool together with its documentation is available through the above home page. Vis5D uses its own data format which makes it necessary to transform your data. Depending on their format and the flowchart on <http://puma.dkrz.de/puma/download/map/> you have the following choices: If

• your data is raw PUMA output.

you need to process it with the pumaburner postprocessor (see section [5\)](#page-44-0) in order to transform it to either NETCDF (option -n or namelist parameter NETCDF=1) or GRIB (option -g or namelist parameter GRIB=1) and proceed from there.

• your data is in SERVICE format, you need to convert it to either GRIB, for instance with the PINGOs: grb copy2 data.srv data_with_grib_metainfo.grb output.grb,

or NETCDF, using the program puma2cdf, which is available with the PUMA postprocessing tools. Despite of its name this program cannot process raw PUMA output but takes SERVICE format as input. It can as well be called as srv2cdf which changes its behaviour: oddities of model output such as the existence of February, $30th$ are then no longer removed. Once the format is changed proceed from there.

- your data is in NETCDF format, it can easily transformed to Vis5D's native format by means of the program cdf2v2d, which is available with the PUMA postprocessing tools.
- your data is in GRIB format, you can find a transformation tool named Grib2V5d at <http://grib2v5d.sourceforge.net> which offers various practical features.

Once the conversion to Vis5D's native format is achieved please follow the instructions from the Vis5D documentation or, if Vis5D is already installed on your system, try finding your own way by typing:

vis5d my_data.v5d

Chapter 7

Column Mode and Soundings

7.1 Setup

The column mode of the the Planet Simulator is an integral part of the full Planet Simulator and not a stand alone model. The advantage of this approach is that all options and modules available in the full model are automatically included in the column mode and that no extra maintenance is necessary.

Technically this is realized by switching off horizontal advection and diffusion which leaves us with an independent column for each grid point. The inclusion of additional options for boundary conditions allows for runs with synchronized columns.

Running the Model at the lowest resolution (T1) with 8 synchronized columns is efficient enough to run very fast column integrations. Using a standard setup with 10 atmospheric layers and a mixed layer ocean one can simulate more than 33500 years per day on a single processor PC (3.3 GHZ CPU).

To make full use of the computer power one can setup an ensemble of columns by specifying boundary conditions for every grid point separately.

7.1.1 Basic switches for column setup

We introduce the macro switch **COLUMN** in the namelist *inp* which is part of the namelist **puma namelist.** By setting $COLUMN = 1$ a default column mode is initialized by setting $\text{YMODE} = \text{"Column"}$, $\text{KICK} = 0$, $\text{NADV} = 0$ and $\text{NHORDIF} = 0$. One can customize the column setup by keeping the default value $COLUMN = 0$ and by setting the other switches individually. For more details see the table inp in appendix [C.](#page-64-0)

7.1.2 Boundary Conditions and forcing

For the T1 truncation the following lower boundary conditions are specified by external fields: The land sea mask $(NO02 \text{ surf } 0172 \text{ .} \text{ s})$, the surface geopotential $(NO02 \text{ .} \text{ surf } 0129 \text{ .} \text{ s})$ and the surface temperature (N002_surf_0169.sra). The other fields are set by default within the model. Some can be set by namelist parameters (see description of standard model).

The surface fluxes of heat and moisture in the column mode can be influenced by the switch **ZUMIN** in the namelist *fluxpar* which sets the surface wind speed entering the bulk exchange scheme. The default value is set to 1 m/s .

Keeping the standard settings the columns will be forced by the solar forcing corresponding to the grid point where the column is located. For the T1 truncation this mean that the columns are located approximately at gaussian latitudes ±35.26◦ . The solar forcing corresponds to the default of the full model. A daily mean insolation is used with an annual cycle. The solar

forcing is also influenced by the climatological ozon distribution which by default also has an annual cycle.

7.2 Graphical User Interface (GUI)

To visualize the time evolution of the column model a vertical Hovmoeller plot has been added to the GUI (picture type: ISOCOL). The sounding device can be also used to visualize the vertical profiles at an arbitrary grid point of the gaussian grid in the full model. By clicking the window the sounding goes from grid point to grid point in meridional direction. The longitude can be selected by the switch **sellon**, which is a parameter of the **inp** namelist in puma namelist. Using the template GUI sounding.cfg in folder plasim/dat the GUI is configured for soundings. In this case sellon can be modified in the control window. For more details see chapter [4.](#page-38-0)

Appendix A

List of Constants and Symbols

Appendix B

Planet Simulator Codes for Variables

Codes available from PUMA-burner (adapted from ECHAM)

- s: PUMA spectral field
- g: PUMA grid point field
- c: computed by PUMA-burner
- a: accumulated

Appendix C

Namelists

C.1 File puma_namelist

C.1.1 Namelist INP

Namelist INP continued

C.1.2 Namelist PLANET

C.1.3 Namelist MISCPAR

C.1.4 Namelist FLUXPAR

C.1.5 Namelist RADPAR

C.1.6 Namelist RAINPAR

C.1.7 Namelist SURFPAR

C.2 File land namelist

C.2.1 Namelist LANDPAR

C.3 File sea namelist

C.3.1 Namelist SEAPAR

C.4 File ocean namelist

C.4.1 Namelist OCEANPAR

C.5 File ice namelist

C.5.1 Namelist ICEPAR

